



More Precision

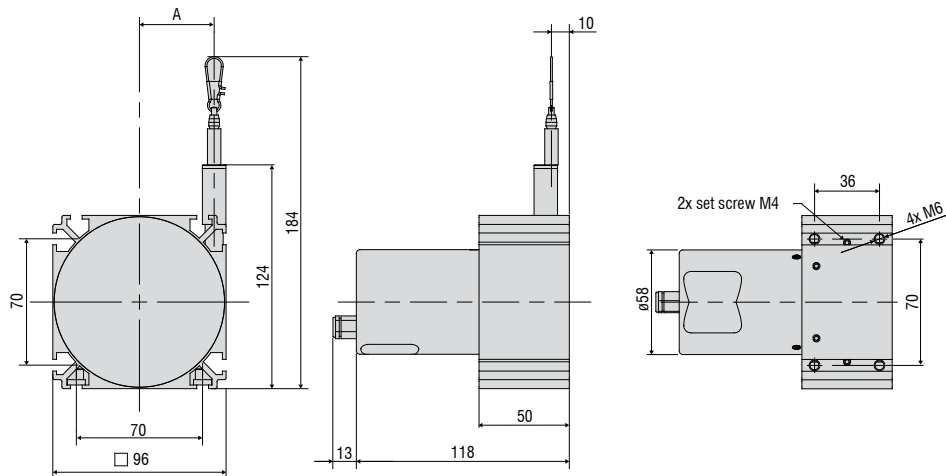
wireSENSOR // Draw-wire displacement sensors



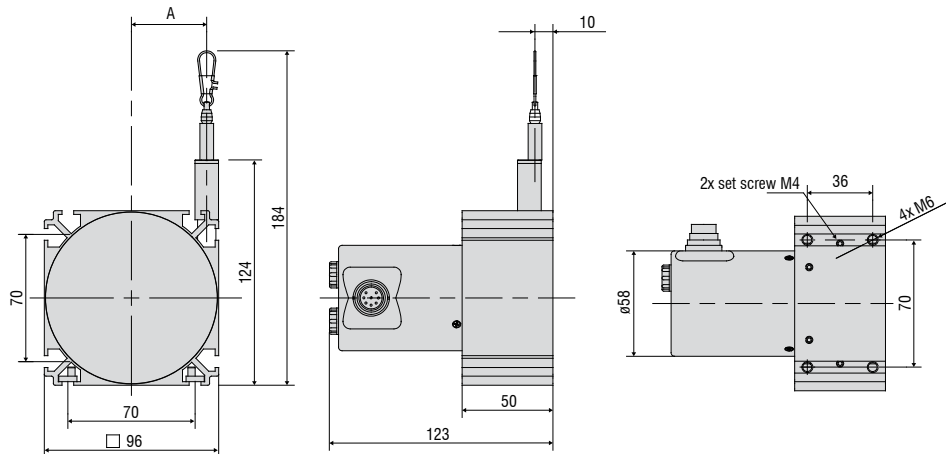


- Robust aluminium profile housing
- Customized versions for OEM
- Potentiometer, current and voltage output

Model P96 Output P



Model P96 Output U/I



Model		WDS-2000-P96	WDS-2500-P96
Output		P/U/I	
Measuring range		2000mm	2500mm
Linearity	<0.1% FSO	<2.0mm	<2.5mm
Resolution		quasi infinite	
Sensor element		hybrid potentiometer	
Temperature range		-20 ... +80 °C	
Material	housing	aluminium	
	draw wire	coated polyamide stainless steel (ø 0.8mm)	
Sensor mounting		slot nuts	
Wire mounting		wire clip	
Wire acceleration		8g	
Wire retraction force (min)		7.5N	5.5N
Wire extension force (max)		11N	9N
Protection class		IP 65 (only if connected)	
Vibration		20g, 20Hz - 2kHz	
Mechanical shock		50g, 10ms	
Electrical connection	P	integrated cable, radial, 1m	
	U, I	flange connector, axial, 8-pin DIN45326	
Weight		appr. 1.1kg	

FSO = Full Scale Output
Specifications for analog outputs on page 51.

Article description

WDS -	2000 -	P96 -	CA -	P
				Output option: P = potentiometer (with connection CA) U = voltage (with connection SR) I = current (with connection SR)
				Connection: SR: radial plug CA: integrated cable, axial, 1m
				Model P96
				Measuring range in mm

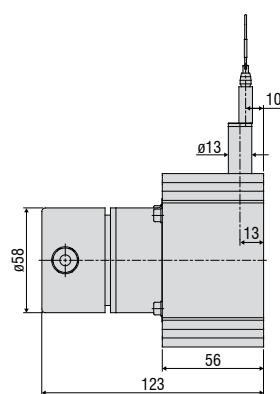
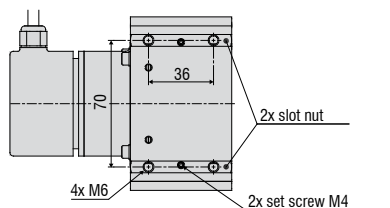
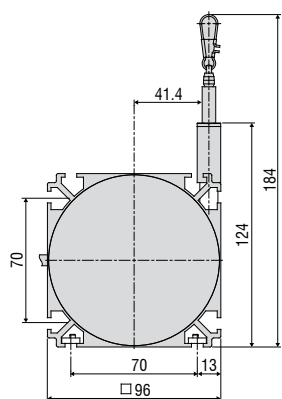


- Robust aluminium profile housing

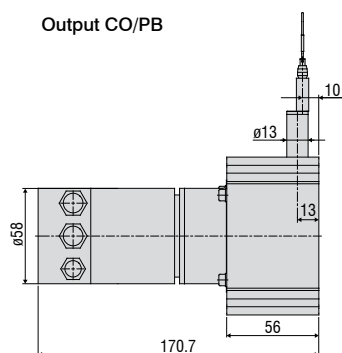
- Incremental / absolute encoder

Model P96

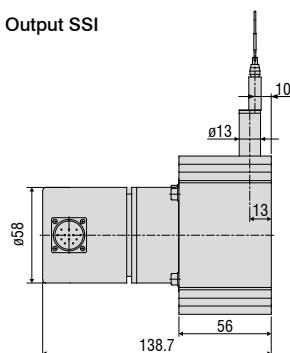
Output HTL/TTL



Output CO/PB



Output SSI



Model		WDS-3000-P96
Output		HTL, TTL, SSI, PB, CO
Measuring range		3000mm
Linearity	<0.02% FSO	<0.6mm
Resolution	HTL, TTL	0.087mm (11.53 pulses/mm)
Resolution	SSI, PB, CO	0.032mm
Sensor element		incremental/absolute encoder
Temperature range		-20 ... +80 °C
Material	housing	aluminium
	draw wire	coated polyamid stainless steel (ø 0.8mm)
Sensor mounting		slot nuts
Wire mounting		wire clip
Wire acceleration		7g
Wire retraction force (min)		5.5N
Wire extension force (max)		9N
Protection class		IP 65 (only if connected)
Vibration		20g, 20Hz - 2kHz
Mechanical shock		50g, 10ms
Electrical connection	HTL, TTL	integrated cable, radial, 1m
	SSI	flange connector, radial, 12-pin
	PB, CO	bus cover
Weight		appr. 1.7kg

FSO = Full Scale Output

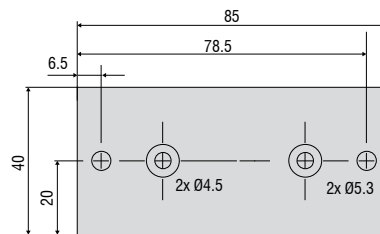
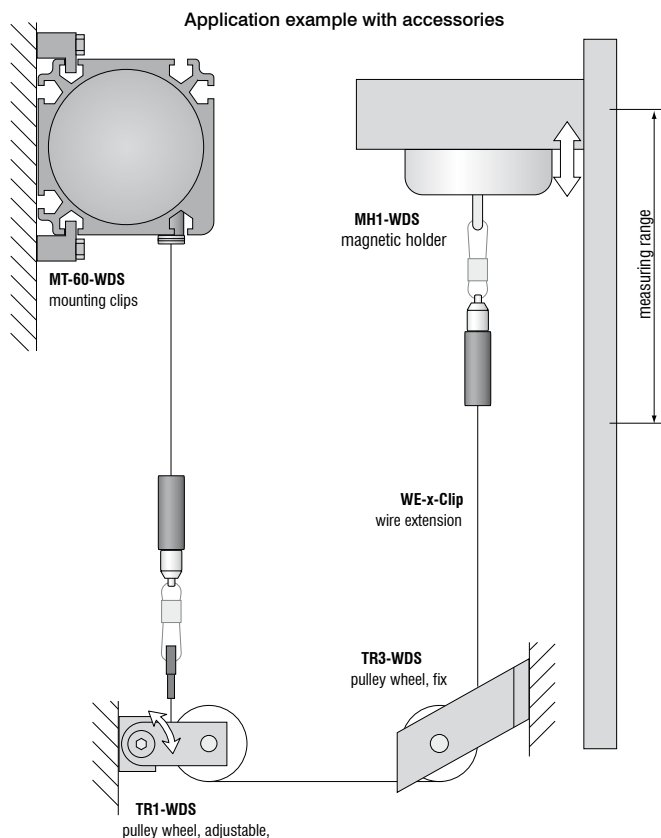
Specifications for digital outputs on page 52.

Article description

WDS -	3000 -	P96 -	CR -	TTL
				Output option: HTL TTL CO: CANopen PB: Profibus DP SSI
				Connection: SR (Output SSI): radial plug CR (Output HTL, TTL): integrated cable, radial, 1m BH (Output CO, PB): bus cover
				Model P96
				Measuring range in mm

Accessories:

WE-xxx-M4	Wire extension with M4-wire connection, x=length
WE-xxx-Clip	Wire extension with eyelet, x=length
TR1-WDS	Pulley wheel, adjustable
TR3-WDS	Pulley wheel, fixed
GK1-WDS	Attachment head for M4
MH1-WDS	Magnetic holder for wire mounting
MH2-WDS	Magnetic holder for sensor mounting
MT-60-WDS	Mounting clamp for WDS-P60
FC8	Female connector for WDS, 8-pin
FC8/90	Female connector 90° for WDS
PC 3/8-WDS	Sensor cable, length 3m
PS 2020	(Power Supply 24 V / 2,5 A, Input 100 - 240 VAC, output 24 VDC / 2.5 A, for snap in mounting on DIN 50022 rail)
WDS-MP60	Mounting plate for P60 sensors



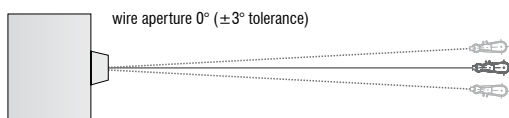
Mounting plate WDS-MP60

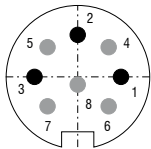
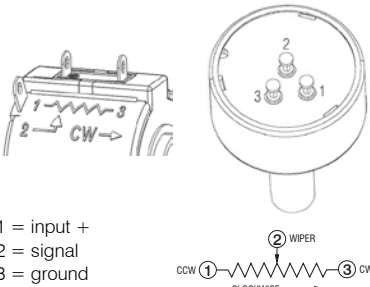

Installation information:

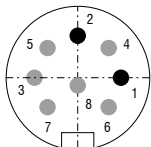
Wire attachment: The free return of the measurement wire is not permissible and it is essential that this is avoided during installation.

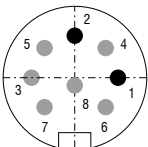
Wire exit angle:

When mounting a draw-wire displacement sensor, a straight wire exit ($\pm 3^\circ$ tolerance) must be taken into account. If this tolerance is exceeded, increased material wear on the wire and at the wire aperture must be expected.



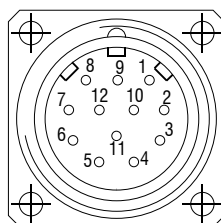
Output		Plug M16 -SA / -SR	Integrated cable -CA / -CR	Open contacts
Potentiometric output (P)		 <p>sensor side</p> <p>1 = input + 2 = ground 3 = signal</p>	white = input + brown = ground green = signal	 <p>1 = input + 2 = signal 3 = ground</p>  <p>1 = input + 2 = signal 3 = ground</p>
Supply voltage	max. 32VDC at 1kOhm / 1 Wmax			
Resistance	1kOhm ±10% (potentiometer)			
Temperature coefficient	±0.0025% FSO/°C			

Voltage output (U)		 <p>sensor side</p> <p>1 = supply 2 = ground 3 = signal 4 = ground</p>	white = supply brown = ground green = signal yellow = ground	
Supply voltage	14 ... 27VDC (non stabilised)			
Current consumption	max. 30mA			
Output voltage	0 ... 10VDC Option 0 ... 5 / ±5V			
Load impedance	>5kOhm			
Signal noise	0.5mV _{eff}			
Temperature coefficient	±0.005% FSO/°C			
Electromagnetic compatibility (EMC)	EN 61000-6-4 EN 61000-6-2			
Adjustment ranges (if supported by the model)				
Zero	±20% FSO			
Sensitivity	±20%			

Current Output (I)		 <p>sensor side</p> <p>1 = supply 2 = ground</p>	white = supply brown = ground	
Supply voltage	14 ... 27VDC (non stabilised)			
Current consumption	max. 35mA			
Output current	4 ... 20mA			
Load	<600Ohm			
Signal noise	<1,6 μA _{eff}			
Temperature coefficient	±0.01% FSO/°C			
Electromagnetic compatibility (EMC)	EN 61000-6-4 EN 61000-6-2			
Adjustment range (if supported by the model)				
Zero	±18% FSO			
Sensitivity	±15%			

Contact description	
1 UB	Encoder power supply connection
2 GND	Encoder ground connection. The voltage drawn to GND is UB.
3 Pulses +	Positive SSI pulse input. Pulse + forms a current loop with pulse -. A current of approx. 7 mA in direction of pulse + input generates a logical 1 in positive logic.
4 Data +	Positive, serial data output of the differential line driver. A High level at the output corresponds to logical 1 in positive logic.
5 ZERO	Zero setting input for setting a zero point at any desired point within the entire resolution. The zeroing process is triggered by a High pulse (pulse duration ≥ 100 ms) and must take place after the rotating direction selection (UP/ DOWN). For maximum interference immunity, the input must be connected to GND after zeroing.
6 Data -	Negative, serial data output of the differential line driver. A High level at the output corresponds to logical 0 in positive logic.
7 Pulses -	Negative SSI pulse input. Pulse - forms a current loop with pulse +. A current of approx. 7 mA in direction of pulse - input generates a logical 0 in positive logic.
8 / 10 DATAVALID DATAVALID MT	Diagnosis outputs \overline{DV} and $\overline{DV MT}$ Jumps in data word, e.g. due to defective LED or photoreceiver, are displayed via the DV output. In addition, the power supply of the multiturn sensor unit is monitored and the DV MT output is set when a specified voltage level is dropped below. Both outputs are Low-active, i.e. are switched through to GND in the case of an error.
9 UP/DOWN	UP/DOWN counting direction input. When not connected, this input is on High. UP/ DOWN-High means increasing output data with a clockwise shaft rotating direction when looking at the flange. UP/ DOWN-Low means increasing values with a counter-clockwise shaft rotating direction when looking at the flange.
11 / 12	Not in use

Pin assignment		
Pin	Cable color	Assignment
1	brown	UB
2	black	GND
3	blue	Pulses +
4	beige	Data +
5	green	ZERO
6	yellow	Data -
7	violet	Pulses -
8	brown/yellow	$\overline{DATAVALID}$
9	pink	UP/ DOWN
10	black/yellow	$\overline{DATAVALID MT}$
11	-	-
12	-	-



Please use leads twisted in pairs for extension cables.

Inputs

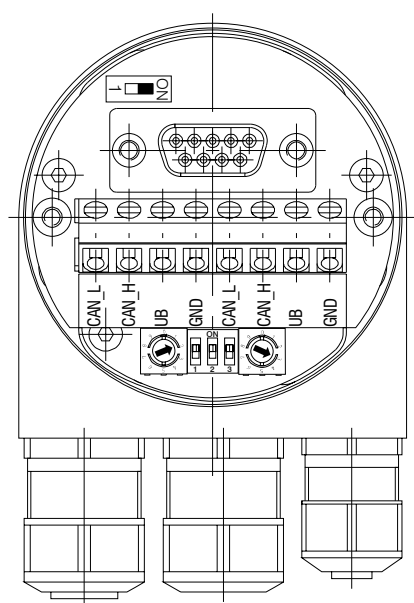
Control signals UP/DOWN and Zero

Level High	> 0.7 UB
Level Low	< 0.3 UB
Connection:	UP/DOWN input with 10kohms to UB, zeroing input with 10kohms to GND.
SSI pulse	
Optocoupler inputs for electrical isolation	

Outputs

SSI data	RS485 driver	
Diagnostic outputs		
Push-pull outputs are short-circuit-proof		
Level High	> UB -3.5V	(with I = -20mA)
Level Low	≤ 0.5V	(with I = 20mA)

CANopen features	
Bus protocol	CANopen
Device profile	CANopen - CiA DSP 406, V 3.0
CANopen Features	Device Class 2, CAN 2.0B
Operating modes (with SDO progr.)	<p>Polling Mode (asynch, via SDO)</p> <p>Cyclic Mode (asynch-cyclic) The encoder cyclically sends the current process actual value without a request by a master. The cycle time can be parameterized for values between 1 and 65535 ms.</p> <p>Synch Mode (synch-cyclic) The encoder sends the current actual process value after receiving a synch telegram sent by a master. The synch counter in the encoder can be parameterized so that the position value is not sent until after a defined number of synch telegrams.</p> <p>Acyclic Mode (synch-acyclic)</p>
Preset value	With the "Preset" parameter the encoder can be set to a desired actual process value that corresponds to the defined axis position of the system. The offset value between the encoder zero point and the mechanical zero point of the system is saved in the encoder.
Rotating direction	With the operating parameter the rotating direction in which the output code is to increase or decrease can be parameterized. Scaling The steps per revolution and the total revolution can be parameterized.
Scaling	The steps per revolution and the total revolution can be parameterized.
Diagnose	<p>The encoder supports the following error messages:</p> <ul style="list-style-type: none"> - Position and parameter error - Lithium cell voltage at lower limit (Multiturn)
Default setting	50kbit/s, node number 1



Setting of terminating Resistor for CANopen



ON = Last user
OFF = User X

Setting CANopen baud rate

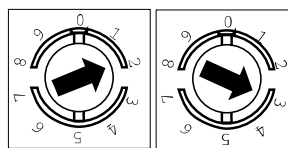
Baud rate	Setting Dip Switch		
	1	2	3
10kBit/s	OFF	OFF	OFF
20kBit/s	OFF	OFF	ON
50kBit/s	OFF	ON	OFF
125kBit/s	OFF	ON	ON
250kBit/s	ON	OFF	OFF
500kBit/s	ON	OFF	ON
800kBit/s	ON	ON	OFF
1MBit/s	ON	ON	ON

Contact description CANopen

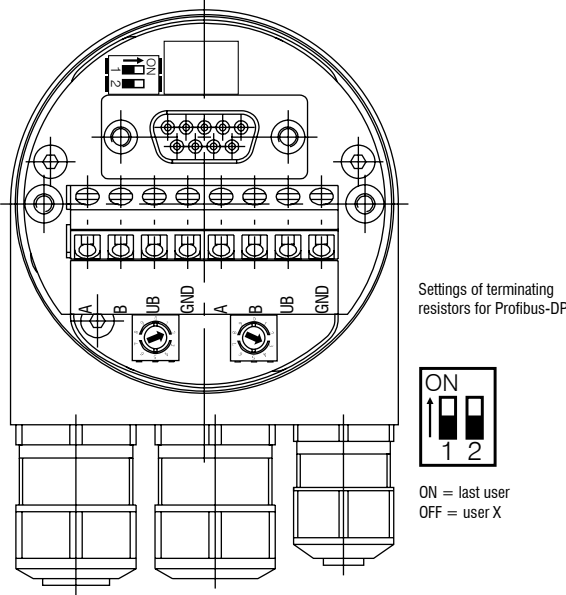
CAN_L	CAN Bus Signal (dominant Low)
CAN_H	CAN Bus Signal (dominant High)
UB	Supply voltage 10...30VDC
GND	Ground contact for UB
	(Terminals with the same designation are internally interconnected)

Settings of user address for CANopen

Address can be set with rotary switch. Example: User address 23

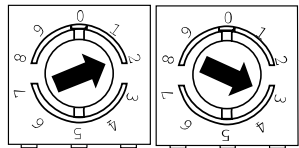


Profibus-DP features	
Bus protocol	Profibus-DP
Profibus features	Device Class 1 and 2
Data exch. functions	Input: Position value Additional parameterized speed signal (readout of the current rotary speed) Output: Preset value
Preset value	With the "Preset" parameter the encoder can be set to a desired actual value that corresponds to the defined axis position of the system.
Parameter functions	Rotating direction: With the operating parameter the rotating direction for which the output code is to increase or decrease can be parameterized.
Diagnose	The encoder supports the following error messages: - Position error - Lithium cell voltage at lower limit (Multiturn)
Default setting	User address 00



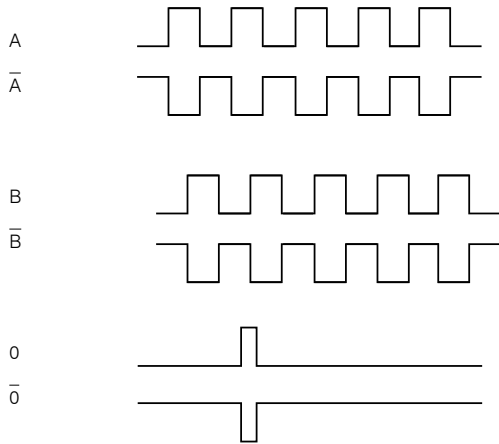
Settings of user address for Profibus-DP

Settings of user address for Profibus-DP



Contact description Profibus-DP
A Negative serial data line
B Positive serial data line
UB Supply voltage 10...30VDC
GND Ground contact for UB
(Terminals with the same designation are internally interconnected)

Signal output



Output TTL	Linedriver (5 VDC)	
Level High	$\geq 2.5V$	(with $I = -20mA$)
Pegel Low	$\leq 0.5V$	(with $I = 20mA$)
Load High	$\leq 20mA$	
Output	A, \bar{A} , B, \bar{B} , 0	

Output TTL01	NPN (5 VDC $\pm 5\%$)	
Level High	$\geq UB - 0.2V$	
Level Low	$0.55 - 0.75V$	
Load High	$\leq 1.85mA$	
Output	A, B, 0	

Output TTL02	Linedriver (5 VDC $\pm 5\%$)	
Level High	$\geq 2.0V$	(with $I = -40mA$)
Level Low	$\leq 0.5V$	(with $I = 40mA$)
Load High	$\leq 40mA$	
Output	A, \bar{A} , B, \bar{B} , 0	

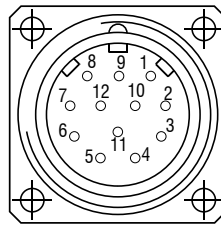
Output HTL	Push-pull (10 ... 30 VDC)	
Level High	$\geq UB - 3V$	(with $I = -20mA$)
Level Low	$\leq 1.5V$	(with $I = 20mA$)
Load High	$\leq 40mA$	
Output	A, \bar{A} , B, \bar{B} , 0	

Output E	Push-pull ((5 VDC)	
Level High	$\geq UB - 2.5V$	
Level Low	$\leq 0.5V$	
Load High	$\leq 50mA$	
Output	A, B, 0	

Output E830	Push-pull ((8 ... 30 VDC)	
Level High	$\geq UB - 3V$	
Level Low	$\leq 2.5V$	
Load High	$\leq 50mA$	
Output	A, B, 0	

Pin assignment TTL, HTL

Pin	Cable color	Assignment
Pin 1	pink	B inv.
Pin 2	blue	UB Sense
Pin 3	red	N (zero impulse)
Pin 4	black	N inv. (zero impulse inv.)
Pin 5	brown	A
Pin 6	green	A inv.
Pin 7	-	-
Pin 8	grey	B
Pin 9	-	-
Pin 10	white/green	GND
Pin 11	white	GND Sense
Pin 12	brown/green	UB



Pin 2 and Pin 12 are internally connected as well as Pin 11 and 10.
For cable length >10m twisted pair wires are required.

Connection assignment E, E830

Cable color	Assignment
white	0V
brown	+UB
green	A
-	\bar{A}
yellow	B
-	\bar{B}
grey	0

Connection assignment TTL01

Cable color	Assignment
brown	0V
grey	+UB
white	A
green	B
yellow	0

Connection assignment TTL02

Cable color	Assignment
red	+UB
black	0V
brown	A
black	\bar{A}
orange	B
black	\bar{B}
yellow	0
black	n.c.